Dissipation and Rheology of Sheared Soft-Core Frictionless Disks Supplemental Material

Daniel Vågberg,¹ Peter Olsson,¹ and S. Teitel²

¹Department of Physics, Umeå University, 901 87 Umeå, Sweden

²Department of Physics and Astronomy, University of Rochester, Rochester, NY 14627

(Dated: April 28, 2014)

RELATIVE MOTION OF CONTACTS

To characterize the nature of the shear-induced particle collisions in our soft-core models, we consider a quantity that we call the angle of contact θ . We define this as the angle that the velocity difference $\mathbf{v}_i - \mathbf{v}_j$ makes with respect to the particle separation $\mathbf{r}_i - \mathbf{r}_j$ for two particles in contact. In Fig. 1 we show plots of the histogram $\mathcal{P}(\theta)$ of the angle of contact θ for our different collisional models. Figs. 1a, b, c are for models CD, CD_n and CD_t respectively, in the strongly inelastic case of Q = 0.1. Fig. 1d is for model CD in the weakly inelastic case of $\phi \gtrsim 0.6$, $\mathcal{P}(\theta)$ shows a strong peak at $\theta = -90^{\circ}$, i.e. we have primarily tangential relative motion at contacts. There is essentially no normal relative motion at $\theta = 0$, except at low ϕ .



FIG. 1. (color online) Histograms of the angle of contact θ for (a) CD, (b) CD_n, and (c) CD_t at Q = 0.1, and (d) CD at Q = 10. Only every fifth symbol is plotted for clarity. Inset to (a) shows the definition of θ .

RHEOLOGICAL CURVES

In Fig. 1 of the main paper we presented plots of the dimensionless elastic part of the pressure $P^{\rm el}$ vs an approviate dimensionless strain rate $\dot{\gamma}\tau_0$ or $\dot{\gamma}\tau_e$. The choice of τ_0 was used for systems with overdamped Newtonian rheology at small Q, while τ_e was used for systems with

inertial Bagnoldian rheology at small Q, so that the data for small Q collapses to a common curve in each case. It is interesting to look at such rheology curves but now plotted with the opposite choice for dimensionless strain rate, i.e. where in Fig. 1 of the main paper we had plotted vs $\dot{\gamma}\tau_0$, here we plot vs $\dot{\gamma}\tau_e$, and vice versa. We show such plots in Figs. 2 below. As should be expected, we now no longer see any simplifying data collapses at any values of Q.



FIG. 2. (color online) Dimensionless pressure $P^{\rm el}$ vs dimensionless strain rate, $\dot{\gamma}\tau_0$ or $\dot{\gamma}\tau_e$, for different values of Q for the four dissipative models defined in the main paper. Left hand column is for packing fraction $\phi = 0.60$; right hand is for $\phi = 0.82$, close below jamming. For each value of Q, several different choices of m_s and k_d were used.

PARTICLE CLUSTERING IN MODEL RD

Our discussion of the relation between rheology and clustering, as shown in Fig. 2 of the main article, was limited to the collisional dissipation CD-models. Here we discuss the situation for the reservoir dissipation model RD.

Newtonian rheology results whenever the dissipative term dominates over the kinetic term. For the CD-models, where energy dissipation is due to binary particle collisions, the strength of the dissipative term depends on how long a given collision lasts (collision time is short when particles separate after colliding, collision time is long when particles stick together after colliding). For RD, a particle's energy dissipation is with respect to the uniform sheared background, with which the particle is always in contact. Hence the dissipative term never becomes negligible and we always have Newtonian rheology at small $\dot{\gamma}$.

The presence of Newtonian rheology in RD is thus not necessarily related to particle clustering as it is for the CD-models. Nevertheless we can still ask how the average contact number z and the percolation probability f_p vary with ϕ for model RD. We show these quantities in Fig. 3 below, for several different strain rates $\dot{\gamma}$ for the

overdamped case of Q = 0.1. We see that the contact number z stays finite for all ϕ , with no strong dependence on $\dot{\gamma}$. Thus particles tend to remain in contact with other particles, unlike the case when one has Bagnold scaling where $z \to 0$ as $\dot{\gamma} \to 0$. The percolation probability stays roughly equal to unity above $\phi \approx 0.6$, but then drops rapidly to zero below. Thus at low ϕ the particles are in clusters, but the clusters do not percolate across the system. We do not yet understand if this percolation transition in RD at $\phi \approx 0.6$ has any physical consequences; it does not appear to effect the rheology.



FIG. 3. (color online) Average contact number z vs ϕ at different strain rates $\dot{\gamma}$ for model RD in the overdamped limit, Q = 0.1. The inset shows the fraction of states f_p with percolating connected clusters.