0. Introduction

These notes will describe five different methods, 1 through 5, for doing simulations of a gas of interacting particles. First some introductory points:

- Adding interactions to the ideal gas.
- The Lennard-Jones interaction.
- Length and time scales.
- Simulation units.
- The Boltzmann distribution.
- Expression for the pressure.

Adding interactions to the ideal gas

The ideal gas—no interactions

$$pV = Nk_BT$$
,

relates pressure times volume to the number of particles, Boltzmann's constant, and the temperature (measured in Kelvin).

Approximate the interaction energy by a sum of pair interactions:

$$U(\{\mathbf{r}\}) = \frac{1}{2} \sum_{i} \sum_{j} u(|\mathbf{r}_{i} - \mathbf{r}_{j}|)$$
$$= \sum_{i} \sum_{j>i} u(|\mathbf{r}_{i} - \mathbf{r}_{j}|).$$

Note: two different ways to avoid double counting. In the code we should use the second!

The Lennard-Jones interaction

The Lennard-Jones interaction:

- attractive at large distances, $\sim -r^{-6}$,
- replusive at short distances, $\sim r^{-12}$.



Taken together this gives the Lennard-Jones potential,

$$u_{\rm LJ}(r) = 4\epsilon \left[\left(\frac{\sigma}{r} \right)^{12} - \left(\frac{\sigma}{r} \right)^6 \right],$$

where σ and ϵ are the length and energy scales of the interaction. The minimum of the potential:

$$r_{\min} = 2^{1/6}\sigma, \qquad u_{\mathrm{LJ}}(r_{\min}) = -\epsilon.$$

Length and time scales

What are the characteristic length, time, and energy scales of a real gas? The parameters of the LJ interaction for Neon atoms are

$$\epsilon = 4.18 \times 10^{-22} \text{ J} \text{ and } \sigma = 3.12 \times 10^{-10} \text{ m}.$$

The typical velocity from $m \langle \mathbf{v}^2 \rangle = 3k_B T$, where "3" is the dimensionality. With

- $m \approx 28 imes 1.67 imes 10^{-26}$ kg for N_2 molecules (typical of air),
- T=300 K (which is 27 °C), $k_B \approx 1.38 imes 10^{-23}$ J/K,

$$\sqrt{\langle \mathbf{v}^2
angle} pprox 10^3 \ {
m m/s}.$$

Time scale of $10^{-13}~{\rm s}=0.1$ ps, since $\sigma\sim 10^{-10}~{\rm m}.$

Simulation units

To use simulations units, let

$$rac{r}{\sigma/{f m}} o r$$
 and $rac{u_{
m LJ}(r)}{\epsilon/{
m J}} o u_{
m LJ}(r)$ and $k_B T/(\epsilon/J) o T,$

where σ/\mathbf{m} (meter) and ϵ/J (Joule) are pure numbers. Note:

- r and $u_{\rm LJ}$ still have dimensions of length and energy,
- $r = \sigma$ in ordinary units is now r = 1.
- The temperature now has dimension of energy.
- We often take m = 1 (instead of something $\times 10^{-26}$ kg).

The Boltzmann distribution

Two different ensembles:

- Microcanonical ensemble—only states with a given energy,
- Canonical ensemble—all energies are possible, controlled by the temperature.

(Including states irrespective of energy often simplifies both analytical calculations and numerical computations.)

A key quantity in the canonical ensemble: the Boltzmann factor, $e^{-E_{\nu}/T}$. The probability of a state is proportional to the Boltzmann factor,

$$P_
u \propto e^{-E_
u/T}.$$

Expression for the pressure

- Molecular dynamics—pressure from the change of momentum the particles bounce off the walls.
- Monte Carlo (no dynamics)—determine pressure from a correlation function!

Starting point: $dF = -SdT - pdV + \mu dN$ gives $p = -\left(\frac{\partial F}{\partial V}\right)_{N,T}$. From $\beta F = -\ln Z$ we get

$$\beta p = \left(\frac{\partial \ln Z}{\partial V}\right)_{N,\beta}, \qquad Z = Z_{\rm kin} Z_{\rm conf},$$

where

$$Z_{\rm conf} = \frac{1}{N!} \int_V d\mathbf{r}_1 \dots d\mathbf{r}_N e^{-\beta U(r^N)}.$$

Differentiate with respect to the integration volume?!

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Expression for the pressure...cont'd

Changing coordinates to $\mathbf{x} = \mathbf{r}/V^{1/d} \Rightarrow dr^N = V^N dx^N$ gives

$$\begin{split} \beta p &= \frac{\partial}{\partial V} \ln \left[V^N \int dx^N e^{-\beta \sum_{i < j} u(V^{1/d} x_{ij})} \right] \\ &= \frac{d}{dV} \ln V^N + \frac{\partial}{\partial V} \ln \left[\int dx^N e^{-\beta U} \right] \\ &= \frac{N}{V} + \left[\int dx^N \left(-\beta \frac{\partial U}{\partial V} \right) e^{-\beta U} \right] / \left[\int dx^N e^{-\beta U} \right]. \end{split}$$

Putting things together we get the virial theorem

$$\beta p = \frac{N}{V} - \frac{\beta}{Vd} \left\langle \sum_{i} \sum_{j>i} r_{ij} u'(r_{ij}) \right\rangle,$$

which in terms of the interparticle force becomes

$$pV = Nk_BT + \frac{1}{d}\left\langle \sum_{i} \sum_{j>i} r_{ij}F_{ij} \right\rangle.$$
(1)

Different kinds of simulations

Five different methods that may be used for simulating a gas.

- i-iii: Different ways to *describe* the system.
- 1-5: Different kinds of dynamics.
 - i) Describe the gas in terms of $\{\mathbf{r}\}$ and $\{\mathbf{v}\}$.
 - 1) Molecular dynamics: ODE deterministic.
 - 2) Langevin dynanics: ODE with a stochastic term.
 - ii) Describe the gas with $\{\mathbf{r}\}$, only.
 - 3) Brownian dynamics: $\Delta \mathbf{r}_i = c \mathbf{F}_i + \text{noise.}$
 - 4) Monte Carlo: No real dynamics. For each particle *i* iterate:
 - ***** suggest a change $\Delta \mathbf{r}_i$ by random,
 - * calculate the change in energy, ΔE_i ,
 - * accept this change with a probability that depends on $\Delta E_i/T$.
- iii) Use a discrete space with positions

 $\mathbf{r}_{\ell} = (0, 0, 0), (0, 0, 1), \dots (0, 0, L-1), \dots (L-1, L-1, L-1).$

5) The lattice gas: Each position either occupied or empty, $n_{\ell} = 0, 1$. Monte Carlo with fluctuating numbers of particles.

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Considerations for MD—Elementary physics

The behavior of a classical gas is fully specified by the Hamiltonian,

$$\mathcal{H}(\{\mathbf{r}\}, \{\mathbf{v}\}) = U(\{\mathbf{r}\}) + K(\{\mathbf{v}\}), \text{ given by}$$
$$U = \frac{1}{2} \sum_{i,j} u(\mathbf{r}_i - \mathbf{r}_j) \text{ and } K = \sum_i \frac{m_i \mathbf{v}_i^2}{2}.$$

The dynamics is given by Newton's second law:

 $m_i \dot{\mathbf{v}}_i = \mathbf{F}_i \equiv -\nabla_i U({\mathbf{r}}), \text{ where } \nabla_i \text{ is differentiation w.r.t. } \mathbf{r}_i.$

For each velocity component the probability distribution is

 $P(v) \propto e^{-mv^2/2T}$, normal distribution—central limit theorem.

and accordingly

$$m\langle v^2 \rangle = T$$
 in terms of energy: $\frac{m}{2}\langle v^2 \rangle = \frac{T}{2}$. (2)

The total energy is a constant. U and K fluctuate during the simulation $\mathcal{A}_{\mathcal{A}}$

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Cutoff in the interaction potential

In an "exact" simulation of a Lennard-Jones gas we would use the potential out to arbitrary distances—very inefficient!

Introduce a cutoff r_c

$$u_{s}(r) = \begin{cases} u_{\mathrm{LJ}}(r) - u_{\mathrm{LJ}}(r_{c}), & r < r_{c}, \\ 0, & r > r_{c}. \end{cases}$$

We can then neglect particles at big distances.

If one also needs a well-behaved second derivative:

$$u_{s}(r) = \begin{cases} u_{\mathrm{LJ}}(r) - u_{\mathrm{LJ}}(r_{c}) + (r_{c} - r) \left. \frac{du_{\mathrm{LJ}}}{dr} \right|_{r_{c}}, & r < r_{c}, \\ 0, & r > r_{c}. \end{cases}$$

How handle the walls? Periodic boundary conditions!

Think of several identical simulation cells placed one after the other with the same particles. Only a mental picture!



- Dynamics: When a particle leaves the system through a wall it simultanously enters the system through the opposite wall.
 Each time a particle coordinate changes, check if the new position is outside the cell, x < 0 or x > L. If so x + L → x or x L → x.
- Forces: Only consider the interaction with the nearest image. To find the nearest image, for directions x, y, and z: $x_{ij} = x_i - x_j$. If $|x_{ij}| > L/2$ either add or subtract L such that $|x_{ij}| < L/2$.

The distance vector is
$$\mathbf{r}_{ij} = (x_{ij}, y_{ij}, z_{ij})$$
.

• The nearest image convention has implications for the smallest possible size of the simulation cell. We need $L \ge 2r_c$.

Integration method

Our basic equations:

 $\dot{\mathbf{r}} = \mathbf{v}, \qquad m\dot{\mathbf{v}} = \mathbf{F}.$

Two good methods with time reversal symmetry:

- The leap from method.
- The velocity Verlet method.

The leap-frog method has positions and forces defined at times $t = n\Delta_t$ whereas velocities are defined at the intermediate times, $t = (n + 1/2)\Delta_t$. With the notation $\mathbf{r}_n \equiv \mathbf{r}(n\Delta_t)$:

$$\mathbf{v}_{n+1/2} = \mathbf{v}_{n-1/2} + (1/m)\mathbf{F}_n\Delta_t, \mathbf{r}_{n+1} = \mathbf{r}_n + \mathbf{v}_{n+1/2}\Delta_t.$$

Note: in the code we always write over the old values with the new ones.

Integration time step

Two considerations when it comes to the time step:

- Stability—otherwise the solution will go to infinity.
- Good precision!

We can only expect a good precision if the steps are small enough that the change in interaction potential in a single step is small.

If the interaction potential changes on the scale ℓ ,

$$\sqrt{\langle \mathbf{v}^2 \rangle} \Delta_t \ll \ell, \quad \text{or} \quad \Delta_t \ll \ell \sqrt{\frac{m}{T}}.$$

In practice: test different time steps and choose one in the range where the measured results only depend very weakly on Δ_t .

Langevin dynamics

- Mostly used as an ODE with a thermostat.
- Originally invented to simulate bigger molecules in a solvent with a large number of smaller molecules. (Big biological molecules in water.)

Idea: include the effect of the smaller molecules in an average way. Good for two reasons:

- A large fraction of the molecules may be eliminated from the calculations.
- The heavier molecules typically move more slowly—we can do with a bigger time step!

Langevin dynamics...cont'd

Add two terms:

- a random force, ζ , adds energy,
- a friction term $-\alpha \mathbf{v}$, dissipates energy.

The equations of motion then become

$$m\dot{\mathbf{v}} = \mathbf{F} - \alpha \mathbf{v} + \boldsymbol{\zeta}.$$

How should the magnitude of ζ be chosen to do a simulation at a desired temperature?

We first need to consider how the noise should be treated.